

NATIONAL POLAR-ORBITING OPERATIONAL ENVIRONMENTAL SATELLITE SYSTEM (NPOESS)

OPERATIONAL ALGORITHM DESCRIPTION DOCUMENT FOR THE GRANULATE ANCILLARY SOFTWARE (D41854 Rev B)

CDRL No. A032

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1.0 INTRODUCTION

1.1 Objective

The purpose of the Operational Algorithm Description (OAD) document is to express, in computer-science terms, the remote sensing algorithms that produce the National Polar-Orbiting Operational Environmental Satellite System (NPOESS) end-user data products. These products are individually known as Raw Data Records (RDRs), Temperature Data Records (TDRs), Sensor Data Records (SDRs) and Environmental Data Records (EDRs). In addition, any Intermediate Products (IPs) produced in the process are also described in the OAD.

The science basis of an algorithm is described in a corresponding Algorithm Theoretical Basis Document (ATBD). The OAD provides a software description of that science as implemented in the operational ground system -- the Data Processing Element (DPE).

The purpose of an OAD is two-fold:

- 1. Provide initial implementation design guidance to the operational software developer.
- 2. Capture the "as-built" operational implementation of the algorithm reflecting any changes needed to meet operational performance/design requirements.

An individual OAD document describes one or more algorithms used in the production of one or more data products. There is a general, but not strict, one-to-one correspondence between OAD and ATBD documents.

1.2 Scope

The scope of this document is limited to the description of the core operational algorithms required to create the Granulated Ancillary products. The theoretical basis for these algorithms is described the VIIRS Earth Gridding Algorithm Theoretical Basis Document ATBD, D43778.

1.3 References

The primary software detailed design documents listed here include science software documents and source code references.

1.3.1 Document References

The science and system engineering documents relevant to the algorithms described in this OAD are listed in Table 1.

Table 1. Reference Documents

Document Title	Document Number/Revision	Revision Date
VIIRS Earth Gridding Algorithm Theoretical Basis Document ATBD (ref Y7051)	D43778 Rev. A	31 July 2008
NPP EDR Production Report	D37005 Rev. D	11 Feb 2009
EDR Interdependency Report	D36385 Rev. E	28 Jan 2009
NPP Mission Data Format Control Book (MDFCB)	D48190-01 Rev A	05 May 2009
CDFCB-X Volume I - Overview	D34862-01 Rev. E	20 May 2009
CDFCB-X Volume II – RDR Formats	D34862-02 Rev. D	03 Jun 2009
CDFCB-X Volume III – SDR/TDR Formats	D34862-03 Rev. D	27 May 2009
CDFCB-X Volume IV Part 1 – IP/ARP/GEO Formats	D34862-04-01 Rev. D	04 Jun 2009

Document Title	Document Number/Revision	Revision Date
CDFCB-X Volume IV Part 2 – Atmospheric, Clouds, and Imagery EDRs	D34862-04-02 Rev. D	04 Jun 2009
CDFCB-X Volume IV Part 3 – Land and Ocean/Water EDRs	D34862-04-03 Rev. D	04 Jun 2009
CDFCB-X Volume IV Part 4 – Earth Radiation Budget EDRs	D34862-04-04 Rev. D	04 Jun 2009
CDFCB-X Volume V - Metadata	D34862-05 Rev. E	14 May 2009
CDFCB-X Volume VI – Ancillary Data, Auxiliary Data, Reports, and Messages	D34862-06 Rev. G	21 May 2009
CDFCB-X Volume VII – NPOESS Downlink Formats	D34862-07-01 Rev. B	27 May 2009
CDFCB-X Volume VIII – Look Up Table Formats	D34862-08 Rev. B	05 Jun 2009
NPP Command and Telemetry (C&T) Handbook	D568423 Rev. C	30 Sep 2008
Data Processor Inter-subsystem Interface Control Document (DPIS ICD)	D35850 Rev. W.1	19 Aug 2009
D35836_G_NPOESS_Glossary	D35836Rev. G	10 Sep 2008
D35838_G_NPOESS_Acronyms	D35838 Rev. G	10 Sep 2008
VIIRS Gridding / Regridding DDD	Y3246 Ver. 5 Rev. 6	17 Sep 2004
VIIRS Gridding / Regridding Component Level Software Architecture	Y3264 Ver. 5 Rev. 6	17 Sep 2004
VIIRS Gridding / Regridding Component ICD	IC60822 Ver. 5 Rev. B	17 Sep 2004
VIIRS Gridding / Regridding Data Dictionary (Area Weighting)	DD60822 Ver. 5 Rev. A	17 Sep 2004
VIIRS-LAND-Albedo-DDD.doc	Y2483 Ver. 5 Rev. 4	24 May 2004
Operational Algorithm Description (OAD) Document for VIIRS Surface Reflectance IP	D38697 Rev. A8	25 Jan 2008
Science Algorithms 2.8 Delivery to IDPS Package Version Description	D39304 Rev	17 Sep 2004
Operational Algorithm Description (OAD) Document for VIIRS Gridded Surface Albedo IP	D39538 Rev. A1	12 Oct 2007
VIIRS Gridding / Regridding Science Grade Software Unit Test Document	D39536 Rev. E	4 Dec 2006
Operational Algorithm Description (OAD) Document for VIIRS Geolocation (GEO) Sensor Data Record (SDR) and Calibration (CAL) SDR	D41868 Rev. A11	22 Feb 2008
Em041210ISIN-M	NP-EMD.2004.510.0054	10 Dec2004
NGAS/AM&S Technical Memo – Instruction for Time and Space Granulation of NWP Ancillary Data	NP-EMD.2006.510.0077 Rev- A	13 Mar 2007
NGAS/AM&S Technical Memo – Instructions to Generating Temperature Ancillary Data for OMPS TC Retrieval	NP-EMD.2007.510.0062	23 Oct 2007

1.3.2 Source Code References

The science and operational code and associated documentation relevant to the algorithms described in this OAD are listed in Table 2.

Table 2. Source Code References

Reference Title	Reference Tag/Revision	Revision Date
VIIRS Gridding/Granulation (G/G) operational software	B1.4 (OAD Rev A1)	22 Jul 2005
VIIRS Gridding/Granulation (G/G) operational software	B1.5 (OAD Rev A4)	19 Sep 2007

VIIRS Gridding/Granulation (G/G) operational software	B1.5.X.1 (OAD Rev A8)	11 Aug 2008
ACCB (no code updates)	OAD Rev A	11 Feb 2009
PCR21311	Sensor Char Build SC-2 (OAD Rev B4)	12 Oct 2009
ACCB (no code changes)	OAD Rev B	17 Mar 2010

2.0 ALGORITHM OVERVIEW

The Granulate Ancillary software prepares ancillary data inputs for use by EDR processing by determining the optimum value of an attribute for the time and space of the observation data and subsequently, this processing is done on a per sensor basis. At its highest level, the Granulate Ancillary component is broken into several distinct parts: granulation of VIIRS ancillary, granulation of CrIMSS ancillary data, and granulation of OMPS TC ancillary data. Each of the previous parts results in granulated products for the respective sensor. OMPS NP uses data produced by OMPS TC granulation.

Granulation of Ancillary data maps external data to the swath. Figure 1 outlines the Granulate Ancillary process.

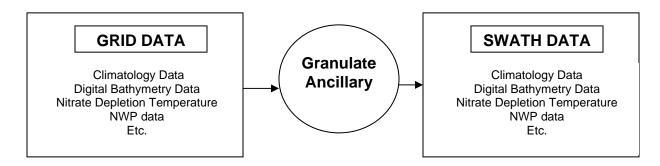


Figure 1. Granulate Ancillary

2.1 Granulate Ancillary Description

The Granulate Ancillary algorithm and theoretical basis for it are described in the VIIRS Gridding/Regridding ATBD, D43778. The current Granulate Ancillary algorithm described in its ATBD, applies for all NPOESS Preparatory Project (NPP) and NPOESS sensors. Granulate Ancillary creates products for VIIRS, CrIS, and OMPS TC.

2.1.1 Interfaces

Granulation of ancillary data may be executed within either a Sensor Data Record (SDR) executable or EDR executable. If a granulated product is needed by multiple downstream algorithms, during normal processing, the SDR algorithm granulates the product after the geolocation data item has been created by the algorithm. If the granulated product is only needed by algorithms within a single process, the granulation may be performed by EDR algorithm. Where the granulation is performed is controlled by configuration guides which accommodate graceful degradation and substitute processing. The Infrastructure Subsystem (INF) provides tasking details (e.g. which granules to process). The Data Management Subsystem (DMS) SI provides data storage and retrieval capability.

2.1.1.1 Inputs

2.1.1.1.1 From Ingest

The external ancillary data and their sources are listed in Table 3. Some of these data are preprocessed by either the factory or the Ingest subsystem.

Table 3. Inputs for the Granulation of Ancillary Data

Input	Description	Sensor
Digital Bathymetry Data	Ocean Depth from University of California at San Diego, SRTM30_PLUS database(http://topex.ucsd.edu/WWW_html/srtm30_plus.html) (units: m; range: -11000 – 9000)	VIIRS
Nitrate Depletion Temperature	Nitrate depletion temperature created by Kendall Carder of Univ of South Florida (Equal angle raster 1024 x 2048) (units: K; range: 271 – 313)	VIIRS
Total Column Ozone	Total Column Ozone from NWP models (units: atm-cm; range: 0.080 – 0.650) (ING converts to atm-cm from Dobson Unit)	VIIRS
Surface Pressure	Surface Pressure in Pa from NWP models (units: hPa; range: 300 – 1080 hPa) (ING converts Pa to hPa)	VIIRS, CrIS, and OMPS TC
Temperature at Pressure Levels	Temperature at NWP levels from NWP models (units: K; range: 150 – 320)	VIIRS, CrIS, OMPS TC
Surface Air Temperature	NCEP GFS (http://www.nws.noaa.gov/climate.html) Air Temperature at 2m (units: K; range: 183 – 328)	VIIRS, CrIS
Skin Temperature	Skin Land/Water Temperature (units: K; range: 180 – 350)	CrIS (used for CrIS GD)
Precipitable Water	Precipitable water in cm from NWP models (units: cm; range: 0 –130) (ING converts from kg/m^2 (kg/m^2 is equivalent to mm) to cm)	VIIRS
Geopotential Height at Pressure Levels	Geopotential height in meters at NWP levels from NWP models (units: gpm; range: -200 – 33000)	VIIRS, CrIS
Tropopause Geopotential Height	Geopotential height of tropopause in meters from NWP models (units: gpm; range: 5000 – 20000)	VIIRS
U-Wind, V- Wind	U & V Wind Components (units: m/s; range: -120 – 120)	VIIRS
Surface Specific Humidity	Specific Humidity at 2m (units: kg/kg; range: 0.002 – 0.040)	VIIRS, CrIS
Surface Geopotential Height	Smoothed height of the earth's surface (units: gpm; range: -1000 – 9000)	VIIRS, CrIS
Terrain Geopotential Height	Terrain Height (geopotential) (units: gpm; range: -1000 – 9000)	VIIRS, CrIS
Cloud Top Pressure	Cloud Top Pressure (units: hPa; range 200 -800)	OMPS TC
Surface Pressure Climatology	Surface Pressure in hPa from TUG87 (units: hPa; range: 475 – 1013.25 hPa)	OMPS TC
UV Surface Reflectance	Fraction of the total possible amount of ultraviolet energy reflected from the surface (Fraction; 0 – 1)	OMPS TC
Temperature Profile Climatology	TOMS V8 temperature profile with data at 11 Umkehr pressure layers (Kelvin; 185 - 290)	OMPS TC

For dynamic ancillary data within time periods not covered by the supplied Ingest products, temporal interpolation is needed. This temporal interpolation is provided by a transient process that is run after Ingest is finished processing ODAD or SDAD. This temporal interpolation process can provide the following inputs for Granulate Ancillary; Surface Pressure, Temperature at Pressure Levels, Surface Air Temperature, Skin Temperature, Water Vapor Mixing Ratio at Pressure Levels, Geopotential Height at Pressure Levels, MSL Pressure, Precipitable Water, Tropopause Height, U-Wind, V-Wind, Surface Specific Humidity, Surface Geopotential Height, and Tropospheric Ozone. See diagram below for a representation of this process.

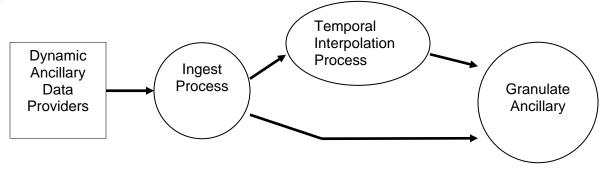


Figure 2: Temporal Interpolation

2.1.1.2 Outputs

Outputs from Granulate Ancillary are mostly products of the same name as those listed in Column 1 of Table 3 except where noted. Outputs have been mapped to the swath at the resolution required by the "consumer" EDR.

2.1.1.2.1 VIIRS Granulate Ancillary

The sub-algorithms invoked by the VIIRS Granulate Ancillary Controller class, ProAncViirsController, correspond one-to-one to each component product enumerated below.

2.1.1.2.1.1 ViirsAncWindSpeedType

This type represents the wind speed and is granulated by the ProAncViirsGranulateWindSpeed sub-algorithm of the ProAncViirsController class. Ancillary inputs are U-Wind and V-Wind.

2.1.1.2.1.2 ViirsAncWindDirectionType

This type represents the wind direction and is granulated by the ProAncViirsGranulateWindDirection sub-algorithm of the ProAncViirsController class. Ancillary inputs are U-Wind and V-Wind.

2.1.1.2.1.3 ViirsAncGeopotentialHeightType

This type represents the geopotential height at pressure layers and is granulated by the ProAncViirsGranulateGeopotentialHeight sub-algorithm of the ProAncViirsController class. Inputs are surface geopotential height, surface temperature, corrected surface pressure, terrain geopotential height, and water vapor mixing ratio.

2.1.1.2.1.4 ViirsAncOzoneType

This type represents the total column ozone and is granulated by the ProAncViirsGranulateOzone sub-algorithm of the ProAncViirsController class.

2.1.1.2.1.5 ViirsAncPrecipWaterType

This type represents the precipitable water and is granulated by the ProAncViirsGranulatePrecipWater sub-algorithm of the ProAncViirsController class.

2.1.1.2.1.6 ViirsAncPresLevelTempType

This type represents the temperature at pressure layers and is granulated by the ProAncViirsGranulatePresLevelTemp sub-algorithm of the ProAncViirsController class.

2.1.1.2.1.7 ViirsAncWaterVaporMixRatioType

This type represents the water vapor mixing ratio at pressure layers and is granulated by the ProAncViirsGranulateWaterVaporMixRatio sub-algorithm of the ProAncViirsController class.

2.1.1.2.1.8 ViirsAncSpecSurfHumidityType

This type represents the surface specific humidity and is granulated by the ProAncViirsGranulateSpecSurfHumidity sub-algorithm of the ProAncViirsController class.

2.1.1.2.1.9 ViirsAncSurfPresType

This type represents the corrected surface pressure and is granulated by the ProAncViirsGranulateSurfPres sub-algorithm of the ProAncViirsController class. Inputs are surface pressure, surface geopotential height, surface specific humidity, surface temperature, and terrain geopotential height.

2.1.1.2.1.10 ViirsAncSurfTempType

This type represents the surface temperature and is granulated by the ProAncViirsGranulateSurfTemp sub-algorithm of the ProAncViirsController class.

2.1.1.2.1.11 ViirsAncTropoGeopotentialHeightType

This type represents the tropopause geopotential height and is granulated by the ProAncViirsGranulateTropoGeopotentialHeight sub-algorithm of the ProAncViirsController class.

2.1.1.2.1.12 ViirsAncSurfGeopotentialHeightType

This type represents the surface geopotential height and is granulated by the ProAncViirsGranulateSurfGeopotentialHeight sub-algorithm of the ProAncViirsController class.

2.1.1.2.1.13 ViirsAncNitrateDepletionType

This type represents the nitrate depletion temperature and is granulated by the ProAncViirsGranulateNitrateDepletion sub-algorithm of the ProAncViirsController class.



2.1.1.2.1.14 ViirsAncBathymetryType

This type represents the digital bathymetry and is granulated by the ProAncViirsGranulateBathymetry sub-algorithm of the ProAncViirsController class.

2.1.1.2.1.15 ViirsAncTerrainHeightType

This type represents the terrain geopotential height and is granulated by the ProAncViirsGranulateGeopotentialTerrainHeight sub-algorithm of the ProAncViirsController class.

2.1.1.2.1.16 ViirsAncSkinTempType

This type represents the skin temperature and is granulated by the ProAncViirs Granulate Skin Tem sub-algorithm of the ProAncViirs Controller class.

2.1.1.2.1.17 ViirsAncOpticalDepthType

This type represents granulation of the Optical Depth data product either from NAAPS, granulated in the ProAncViirsOpticalDepth sub-algorithm or the AOT Climatology file, which is granulated in the ProAncViirsGranulateAotClimatology sub-algorithm, Both are sub-algorithms of the ProAncViirsController class.

2.1.1.2.2 CrIMSS Granulate Ancillary

The sub-algorithms invoked by the CrIS Granulate Ancillary Controller class, ProAncCrisController, correspond one-to-one to each component product enumerated below.

2.1.1.2.2.1 CrisAncTerrainHeightType

This type represents the terrain geopotential height and is granulated by the ProAncCrisGranulateGeopotentialTerrainHeight sub-algorithm of the ProAncCrisController class.

2.1.1.2.2.2 CrisAncPresLevelTempType

This type represents the temperature at pressure layers and is granulated by the ProAncCrisGranulatePresLevelTemp sub-algorithm of the ProAncCrisController class.

2.1.1.2.2.3 CrisAncSurfPresType

This type represents the corrected surface pressure and is granulated by the ProAncCrisGranulateSurfPres sub-algorithm of the ProAncCrisController class. Inputs are surface pressure, surface geopotential height, surface specific humidity, surface temperature, and terrain geopotential height.

2.1.1.2.2.4 CrisAncSurfGeopotentialHeightType

This type represents the surface geopotential height and is granulated by the ProAncCrisGranulateSurfGeopotentialHeight sub-algorithm of the ProAncCrisController class.

2.1.1.2.2.5 CrisAncSurfTempType



This type represents the surface temperature and is granulated by the ProAncCrisGranulateSurfTemp sub-algorithm of the ProAncCrisController class.

2.1.1.2.2.6 CrisAncPresLevelMixRatioType

This type represents the water vapor mixing ratio at pressure layers and is granulated by the ProAncCrisGranulateWaterVaporMixRatio sub-algorithm of the ProAncCrisController class.

2.1.1.2.2.7 CrisAncSpecSurfHumidityType

This type represents the surface specific humidity and is granulated by the ProAncCrisGranulateSpecSurfHumidity sub-algorithm of the ProAncCrisController class.

2.1.1.2.3 OMPS TC Granulate Ancillary

The sub-algorithms invoked by the OMPS TC Granulate Ancillary Controller class, ProAncOmpsTcController, correspond one-to-one to each product enumerated below.

2.1.1.2.3.1 OmpsTcAncSurfPresType

This type represents the surface pressure and is granulated by the ProAncOmpsTcGranulateSurfPres sub-algorithm of the ProAncOmpsTcController.

2.1.1.2.3.2 OmpsTcAncCloudTopPresType

This type represents the cloud top pressure and is granulated by the ProAncOmpsTcGranulateCloudTopPres sub-algorithm of the ProAncOmpsTcController. The ancillary input is cloud top pressure.

2.1.1.2.3.3 OmpsTcAncUVSurfReflectType

This type represents the ultraviolet surface reflectance and is granulated by the ProAncOmpsTcGranulateUVSurfReflect sub-algorithm of the ProAncOmpsTcController. The ancillary input is ultraviolet surface reflectance.

2.1.1.2.3.4 OmpsTcAncPresLevelTempType

This type represents the atmospheric temperature profile at Umkehr pressure layers and is granulated by the ProAncOmpsTcGranulatePresLayerTemp sub-algorithm of the ProAncOmpsTcController. Two ancillary data inputs are required. The first ancillary input is temperature profile forecast data. The second ancillary input is the TOMS V8 temperature profile climatology, which is at Umkehr pressure layers. The temperature profile forecast data is used to populate Umkehr layers 1-7. Multiple pressure levels of the forecast data are "binned" into a single Umkehr layer. Because forecast data does not extend high enough into the atmosphere to populate Umkehr layers 8-11, data from the TOMS V8 climatology is used at these layers.

2.1.2 Algorithm Processing

Granulate Ancillary software is implemented based on its distinct function described as follows:

• Granulate Ancillary: Referencing external ancillary gridded data to a sensor's swath.



Because interpolation is done in map grid coordinates, no special code is required to handle irregularity at the poles or discontinuity at 180 degrees longitude.

As indicated in Section 2.1.1.2, each specific ancillary data product is granulated by a respective class. The granulation algorithms copy the data out of the grid and apply specific resampling needed for that product.

2.1.2.1 Main Module

Granulate Ancillary's function is to resample ancillary information from a grid to the swath of a sensor. Ancillary products come in a variety of projection grids--e.g. Cylindrical Equidistant and Polar Stereographic. The resampling is accomplished by use of a sensor specific Mapping Factory class for each sensor. The mapping classes are used to create a MDS (Map Data Set) which contains the mapping swath latitude and longitude to grid cell. The mapping classes return a structure (of type Grid2ModViirsGranule, Grid2CrisGranule, or Grid2OmpsTcGranule) that maps each swath pixel used in the spatial bilinear interpolation to a grid row, column, and source (North, South for Polar Stereographic)—i.e. the swath data is mapped to a grid where the interpolation is executed.

Currently, Digital Bathymetry and Terrain Geopotential Height (SRTM30_PLUS) data are resampled using Nearest Neighbor. The remaining Ancillary products use bilinear interpolation from sensor utility classes (used to go from swath to grid) for resampling.

2.1.3 Graceful Degradation

There are two cases where input graceful degradation is indicated in the Granulate Ancillary product.

- 1. The primary input denoted in the algorithm configuration guide can not be successfully retrieved but alternate input can be retrieved.
- 2. Graceful degradation is indicated when an input Anc Int item (NCEP, NOGAPS, NAAPS, Earth Orientation) are found to be using an extended forecast.

Table 4 details the instances of these two cases for Gran Anc. Note that the shaded cells indicate that the graceful degradation was done upstream at product production.

Table 4. Graceful Degradation Detail

Description	Baseline Data Source	Primary Backup Data	Secondary Backup	Tertiary Backup Data	Graceful Degradation
		Source	Data	Source	Done
			Source		Upstream

Digital Bathymetry Database	VIIRS_GD_12.4.1 SRTM30_PLUS	N/A	N/A	N/A	No
Geopotential Height Profile	VIIRS_GD_11.4.4 NCEP	VIIRS_GD_11. 4.4 NCEP (Extended Forecast)	N/A	N/A	No
Nitrate Depletion Temperatures	VIIRS_GD_13.4.1 Univ. of Florida (Kendal Carder) database	N/A	N/A	N/A	No
Total Column Ozone	VIIRS_GD_09.4.1 NCEP	VIIRS_GD_09. 4.1 NCEP (Extended Forecast)	N/A	N/A	No
Total Column Precipitable Water	VIIRS_GD_09.4.1 1 NCEP	VIIRS_GD_11. 4.3 NCEP (Extended Forecast)	N/A	N/A	No
Atmospheric Temperature Profile, VIIRS and CrIS	VIIRS_GD_11.4.3 NCEP	VIIRS_GD_11. 4.3 NCEP (Extended Forecast)	N/A	N/A	No
Atmospheric Temperature Profile, OMPS TC	OMPS_GD_01.4. 3 NCEP/Climatology	OMPS_GD_01 .4.3 NCEP/Climatol ogy (EF)	OMPS_GD _01.4.9 Climatology	N/A	No
Skin Temperature	NCEP	NCEP (Extended Forecast)	N/A	N/A	No
Specific Humidity at Surface	VIIRS_GD_09.4.1 2 NCEP	VIIRS_GD_09. 4.12 NCEP (Extended Forecast)	N/A	N/A	No
Geopotential Surface Height	NCEP	NCEP (Extended Forecast)	N/A	N/A	No
Adjusted Surface Pressure, VIIRS and CrIS	VIIRS_GD_28.4.1 NCEP	VIIRS_GD_28. 4.1 NCEP (Extended Forecast)	N/A	N/A	No
Surface Pressure, OMPS TC	OMPS_GD_01.4. 2 NCEP	OMPS_GD_01 .4.2 NCEP (EF)	OMPS_GD _01.4.8 TUG87	N/A	No
Surface Air Temperature	VIIRS_GD_09.4.1 0 NCEP	VIIRS_GD_09. 4.10 NCEP(Extende d Forecast)	N/A	N/A	No
Tropopause Height	VIIRS_GD_09.4.6 NCEP	VIIRS_GD_09. 4.6 NCEP (Extended Forecast)	N/A	N/A	No
Terrain Geopotential Height	NCEP	NCEP (Extended Forecast)	N/A	N/A	No
Water Vapor Mixing Ratio at Pressure Levels	ALL_GD_01.4.4 NCEP	ALL_GD_01.4. 4 NCEP (Extended Forecast)	N/A	N/A	No
Sea Surface Wind Speed and Direction	ALL_GD_01.4.2 NCEP	ALL_GD_01.4. 2 NCEP (Extended Forecast)	N/A	N/A	No

Aerosol Optical Thickness	VIIRS_GD_27.4.1 NAAPS	VIIRS_DG_27. 4.1 NAAPS	VIIRS_GD_ 15.4.1	N/A	No
		(Extended Forecast)	Climatology		
Cloud Top Pressure	OMPS_GD_01.4.	N/A	N/A	N/A	No
Climatology	1				
	Climatology				
Ultra Violet Surface	OMPS_GD_01.4.	N/A	N/A	N/A	No
Reflectivity	11				
	Climatology				

2.1.4 Exception Handling

The code for bilinear interpolation of data from the grid to a swath verifies that all points are valid before doing the interpolation. If any of the input grid points are invalid or fill, the interpolation is not done and the pixel will be filled with a fill value. Geolocation containing fill data results in the respective pixel of the granulated product being set to fill. Geolocation containing invalid data that is not fill data will cause the algorithm to fail.

2.1.5 Data Quality Monitoring

No data quality monitoring tests are performed on this IP.

2.1.6 Computational Precision Requirements

The computation requirements for Granulate Ancillary mirror those of the products it produces and consumes. For the most part, single precision floating-point precision is required.

2.1.7 Algorithm Support Considerations

The DMS and INF must be running before any of the Granulate Ancillary products can be executed. A C++ compiler is needed to compile the algorithms.

2.1.8 Assumptions and Limitations

This section discusses the assumptions and limitations associated with the algorithms.

2.1.8.1 Assumptions

All necessary data is available and provided within the necessary time constraints.

2.1.8.2 Limitations

None.



3.0 GLOSSARY/ACRONYM LIST

3.1 Glossary

The current glossary for the NPOESS program, D35836_G_NPOESS_Glossary, can be found on eRooms. Table 5 contains those terms most applicable for this OAD.

Table 5. Glossary

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Term	Description
Algorithm	A formula or set of steps for solving a particular problem. Algorithms can be expressed in any language, from natural languages like English to mathematical expressions to programming languages like FORTRAN. On NPOESS, an algorithm consists of: A theoretical description (i.e., science/mathematical basis)
	A computer implementation description (i.e., method of solution) A computer implementation (i.e., code).
Algorithm Configuration Control Board (ACCB)	Interdisciplinary team of scientific and engineering personnel responsible for the approval and disposition of algorithm acceptance, verification, development and testing transitions. Chaired by the Algorithm Implementation Process Lead, members include representatives from IWPTB, Systems Engineering & Integration IPT, System Test IPT, and IDPS IPT
Algorithm Verification	Science-grade software delivered by an algorithm provider is verified for compliance with data quality and timeliness requirements by Algorithm Team science personnel. This activity is nominally performed at the IWPTB facility. Delivered code is executed on compatible IWPTB computing platforms. Minor hosting modifications may be made to allow code execution. Optionally, verification may be performed at the Algorithm Provider's facility if warranted due to technical, schedule or cost considerations.
Ancillary Data	Any data which is not produced by the NPOESS System, but which is acquired from external providers and used by the NPOESS system in the production of NPOESS data products.
EDR Algorithm	Scientific description and corresponding software and test data necessary to produce one or more environmental data records. The scientific computational basis for the production of each data record is described in an ATBD. At a minimum, implemented software is science-grade and includes test data demonstrating data quality compliance.
Environmental Data Record (EDR)	[IORD Definition] Data record produced when an algorithm is used to convert Raw Data Records (RDRs) to geophysical parameters (including ancillary parameters, e.g., cloud clear radiation, etc.). [Supplementary Definition] An Environmental Data Record (EDR) represents the state of the environment, and the related information needed to access and understand the record. Specifically, it is a set of related data items that describe one or more related estimated environmental parameters over a limited time-space range. The parameters are located by time and Earth coordinates. EDRs may have been resampled if they are created from multiple data sources with different sampling patterns. An EDR is created from one or more NPOESS SDRs or EDRs, plus ancillary environmental data provided by others. EDR metadata contains references to its
Model Validation	processing history, spatial and temporal coverage, and quality. The process of determining the degree to which a model is an accurate representation of the real-world from the perspective of the intended uses of the model. [Ref.: DoDD 5000.59-DoD Modeling and Simulation Management]
Model Verification	The process of determining that a model implementation accurately represents the developer's conceptual description and specifications. [Ref.: DoDD 5000.59-DoD Modeling and Simulation Management]
Operational Code	Verified science-grade software, delivered by an algorithm provider and verified by IWPTB, is developed into operational-grade code by the IDPS IPT.
Operational-Grade Software	Code that produces data records compliant with the System Specification requirements for data quality and IDPS timeliness and operational infrastructure. The software is modular relative to the IDPS infrastructure and compliant with IDPS application programming interfaces (APIs) as specified for TDR/SDR or EDR code.

Term	Description
Raw Data Record	[IORD Definition]
(RDR)	Full resolution digital sensor data, time referenced and earth located, with absolute radiometric and geometric calibration coefficients appended, but not applied, to the data. Aggregates (sums or weighted averages) of detector samples are considered to be full resolution data if the aggregation is normally performed to meet resolution and other requirements. Sensor data shall be unprocessed with the following exceptions: time delay and integration (TDI), detector array non-uniformity correction (i.e., offset and responsivity equalization), and data compression are allowed. Lossy data compression is allowed only if the total measurement error is dominated by error sources other than the data compression algorithm. All calibration data will be retained and communicated to the ground without lossy compression. [Supplementary Definition] A Raw Data Record (RDR) is a logical grouping of raw data output by a sensor, and related information needed to process the record into an SDR or TDR. Specifically, it is a set of
	unmodified raw data (mission and housekeeping) produced by a sensor suite, one sensor, or a reasonable subset of a sensor (e.g., channel or channel group), over a specified, limited time range. Along with the sensor data, the RDR includes auxiliary data from other portions of NPOESS (space or ground) needed to recreate the sensor measurement, to correct the measurement for known distortions, and to locate the measurement in time and space, through subsequent processing. Metadata is associated with the sensor and auxiliary data to permit its effective use.
Retrieval	A science-based algorithm used to 'retrieve' a set of environmental/geophysical parameters
Algorithm Science Algorithm	(EDR) from calibrated and geolocated sensor data (SDR). Synonym for EDR processing. The theoretical description and a corresponding software implementation needed to produce
	an NPP/NPOESS data product (TDR, SDR or EDR). The former is described in an ATBD. The latter is typically developed for a research setting and characterized as "science-grade".
Science Algorithm Provider	Organization responsible for development and/or delivery of TDR/SDR or EDR algorithms associated with a given sensor.
Science-Grade Software	Code that produces data records in accordance with the science algorithm data quality requirements. This code, typically, has no software requirements for implementation
	language, targeted operating system, modularity, input and output data format or any other design discipline or assumed infrastructure.
SDR/TDR Algorithm	Scientific description and corresponding software and test data necessary to produce a Temperature Data Record and/or Sensor Data Record given a sensor's Raw Data Record. The scientific computational basis for the production of each data record is described in an Algorithm Theoretical Basis Document (ATBD). At a minimum, implemented software is science-grade and includes test data demonstrating data quality compliance.
Sensor Data	[IORD Definition]
Record (SDR)	Data record produced when an algorithm is used to convert Raw Data Records (RDRs) to calibrated brightness temperatures with associated ephemeris data. The existence of the SDRs provides reversible data tracking back from the EDRs to the Raw data. [Supplementary Definition]
	A Sensor Data Record (SDR) is the recreated input to a sensor, and the related information needed to access and understand the record. Specifically, it is a set of incident flux estimates made by a sensor, over a limited time interval, with annotations that permit its effective use. The environmental flux estimates at the sensor aperture are corrected for
	sensor effects. The estimates are reported in physically meaningful units, usually in terms of an angular or spatial and temporal distribution at the sensor location, as a function of spectrum, polarization, or delay, and always at full resolution. When meaningful, the flux is also associated with the point on the Earth geoid from which it apparently originated. Also, when meaningful, the sensor flux is converted to an equivalent top-of-atmosphere (TOA) brightness. The associated metadata includes a record of the processing and sources from which the SDR was created, and other information needed to understand the data.
Temperature Data Record (TDR)	[IORD Definition] Temperature Data Records (TDRs) are geolocated, antenna temperatures with all relevant calibration data counts and ephemeris data to revert from T-sub-a into counts.
	[Supplementary Definition] A Temperature Data Record (TDR) is the brightness temperature value measured by a microwave sensor, and the related information needed to access and understand the record. Specifically, it is a set of the corrected radiometric measurements made by an imaging microwave sensor, over a limited time range, with annotation that permits its effective use. A TDR is a partially-processed variant of an SDR. Instead of reporting the estimated microwave flux from a specified direction, it reports the observed antenna brightness temperature in that direction.

3.2 Acronyms

The current acronym list for the NPOESS program, D35838_G_NPOESS_Acronyms, can be found on eRooms. Table 6 contains those terms most applicable for this OAD.

Table 6. Acronyms

Term	Expansion
AM&S	Algorithms, Models & Simulations
API	Application Programming Interfaces
ARP	Application Related Product
CDFCB-X	Common Data Format Control Book - External
DMS	Data Management Subsystem
DPIS ICD	Data Processor Inter-subsystem Interface Control Document
DQTT	Data Quality Test Table
INF	Infrastructure
ING	Ingest
IP	Intermediate Product
LUT	Look-Up Table
MDFCB	Mission Data Format Control Book
QF	Quality Flag
SDR	Sensor Data Record
SI	International System of Units
TBD	To Be Determined
TBR	To Be Resolved
TOA	Top of the Atmosphere
VCM	VIIRS Cloud Mask

4.0 **OPEN ISSUES**

Table 7. TBXs

TBX ID	Title/Description	Resolution Date
None		